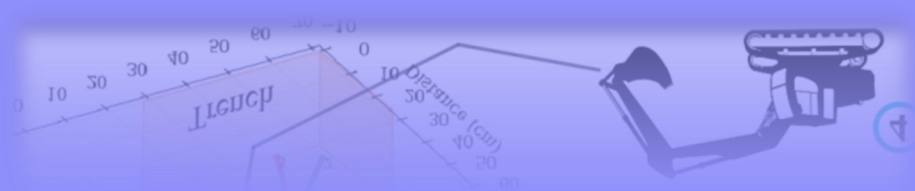
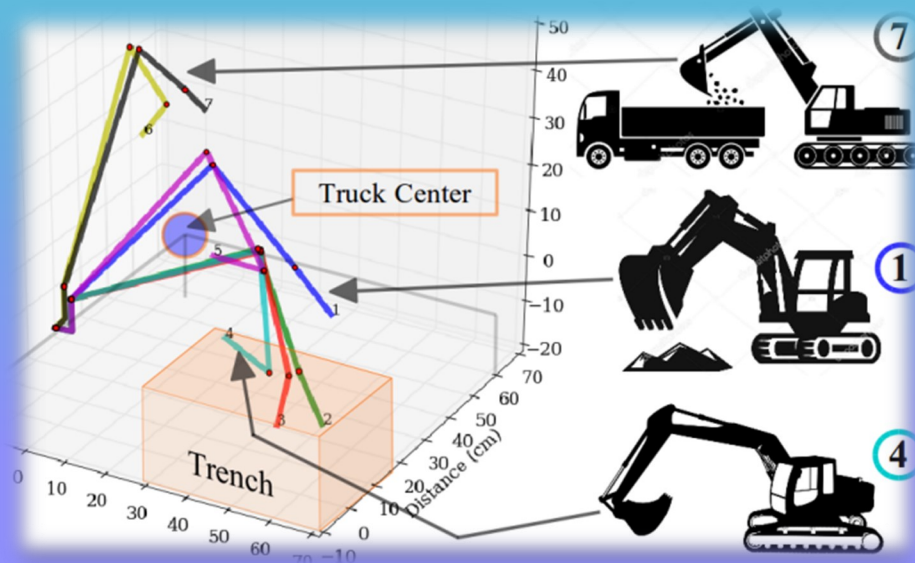


PUBLICATIONS CONTENT DIGEST



CSS Publications Activities

Vice-President

ANDREW ALLEYNE *University of Illinois at Urbana-Champaign*
<http://ieeecss.org/publications>

Journal Editors

IEEE Transactions on Automatic Control

ALESSANDRO ASTOLFI *Imperial College London and University of Rome “Tor Vergata”*
<http://ieeecss.org/publication/transactions-automatic-control>

IEEE Transactions on Control Systems Technology

ANDREA SERRANI *Ohio State University*
<http://ieeecss.org/publication/transactions-control-systems-technology>

IEEE Transactions on Control of Network Systems

JEFF SHAMMA *University of Illinois at Urbana-Champaign*
ANNA SCAGLIONE Deputy Editor-in-Chief *Arizona State University*
<http://ieeecss.org/publication/transactions-control-network-systems>

IEEE Control Systems Letters

MARIA ELENA VALCHER *University of Padua*
<http://ieeecss.org/publication/control-systems-letters>

IEEE Control Systems Magazine

RODOLPHE SEPULCHRE *University of Cambridge*
<http://ieeecss.org/publication/ieee-control-systems-magazine>

IEEE Open Journal of Control Systems

SONIA MARTINEZ *University of California, San Diego*
<http://ieeecss.org/publication/open-journal-control-systems>

Electronics Editors

CSS State-Space Forum

AHMAD TAHA *Vanderbilt University*
ANKUSH CHAKRABARTY *Mitsubishi Electric Research Laboratories*
<https://state-space.ieeecss.org>

***Submission and editorial instructions can be found on each publication’s homepage**

IEEE TRANSACTIONS ON AUTOMATIC CONTROL

A PUBLICATION OF THE IEEE CONTROL SYSTEMS SOCIETY



JANUARY 2022

VOLUME 67

NUMBER 1

IETAA9

(ISSN 0018-9286)

REGULAR PAPERS

Safety Verification and Robustness Analysis of Neural Networks via Quadratic Constraints and Semidefinite Programming <i>M. Fazlyab, M. Morari, and G. J. Pappas</i>	1
The Effect of Time Delay on the Average Data Rate and Performance in Networked Control Systems <i>M. Barforooshan, M. S. Derpich, P. A. Stavrou, and J. Østergaard</i>	16
Generalized Proportional Allocation Policies for Robust Control of Dynamical Flow Networks <i>G. Nilsson and G. Como</i>	32
Harmonic Based Model Predictive Control for Set-Point Tracking <i>P. Krupa, D. Limon, and T. Alamo</i>	48
H_∞ Event-Triggered Control With Performance Guarantees Vis-à-Vis the Optimal Periodic Solution <i>L. Mi and L. Mirkin</i>	63
Control of Real-Time Systems With Integer Parameters <i>A. Jovanović, D. Lime, and O. H. Roux</i>	75
Robust and Adaptive Sequential Submodular Optimization <i>V. Tzoumas, A. Jadbabaie, and G. J. Pappas</i>	89
An Analytic Interpolation Approach to Stability Margins With Emphasis on Time Delay <i>A. Ringh, J. Karlsson, and A. Lindquist</i>	105
On the Strong \mathcal{H}_2 Norm of Differential Algebraic Systems With Multiple Delays: Finiteness Criteria, Regularization, and Computation <i>M. A. Gomez, R. M. Jungers, and W. Michiels</i>	121
Observer Design for a Class of Semilinear Hyperbolic PDEs With Distributed Sensing and Parametric Uncertainties <i>H. Holta and O. M. Aamo</i>	134
Input Delay Tolerance of Nonlinear Systems Under Smooth Feedback: A Semiglobal Control Framework <i>Y. Wang and W. Lin</i>	146
From Noisy Data to Feedback Controllers: Nonconservative Design via a Matrix S-Lemma <i>H. J. van Waarde, M. K. Camlibel, and M. Mesbahi</i>	162
Probabilistic Model Predictive Safety Certification for Learning-Based Control <i>K. P. Wabersich, L. Hewing, A. Carron, and M. N. Zeilinger</i>	176
Stochastic Adaptive Optimization With Dithers <i>S. Xie, S. Liang, L. Y. Wang, G. Yin, and W. Chen</i>	189
Asymptotic Tracking and Linear-Like Behavior Using Multi-Model Adaptive Control <i>M. T. Shahab and D. E. Miller</i>	203
Event-Triggered Output-Feedback Backstepping Control of Sandwich Hyperbolic PDE Systems <i>J. Wang and M. Krstic</i>	220
Asymptotically Optimal Lagrangian Priority Policy for Deadline Scheduling With Processing Rate Limits <i>L. Hao, Y. Xu, and L. Tong</i>	236
Accelerated Point-Wise Maximum Approach to Approximate Dynamic Programming <i>P. N. Beuchat, J. Warrington, and J. Lygeros</i>	251

(Contents Continued on Back Cover)



Structural Completeness of a Multichannel Linear System With Dependent Parameters	<i>F. Liu and A. S. Morse</i>	267
Asymptotical Stability and Stabilization of Continuous-Time Probabilistic Logic Networks	<i>Y. Guo, Z. Li, Y. Liu, and W. Gui</i>	279
High-Gain Observer Design for a Class of Quasi-Linear Integro-Differential Hyperbolic Systems—Application to an Epidemic Model	<i>C. Kitsos, G. Besançon, and C. Prieur</i>	292
Ultimately Bounded Filtering Subject to Impulsive Measurement Outliers	<i>L. Zou, Z. Wang, J. Hu, and H. Dong</i>	304
Stochastic Control With Affine Dynamics and Extended Quadratic Costs	<i>S. Barratt and S. Boyd</i>	320

TECHNICAL NOTES

On the Use of the Time-Integrals of the Output in Observer Design for Nonlinear Autonomous Systems	<i>L. Menini, C. Possieri, and A. Tornambe</i>	336
Abstraction of the Supervisory Control Solution to Deal With Planning Problems in Manufacturing Systems	<i>P. N. Pena, J. N. Vilela, M. R. C. Alves, and G. C. Rafael</i>	344
Digital Implementation of Derivative-Dependent Control by Using Delays for Stochastic Multiagents	<i>J. Zhang and E. Fridman</i>	351
Discrete Event Dynamic Modeling and Analysis of the Democratic Progress in a Society Controlled by Networked Agents	<i>S.-J. Park and K.-H. Cho</i>	359
Hyperbolic-SVD-Based Square-Root Unscented Kalman Filters in Continuous-Discrete Target Tracking Scenarios	<i>G. Yu, Kulikov and M. V. Kulikova</i>	366
An Adaptive Kalman Filter With Inaccurate Noise Covariances in the Presence of Outliers	<i>H. Zhu, G. Zhang, Y. Li, and H. Leung</i>	374
Optimal Controller Synthesis and Dynamic Quantizer Switching for Linear-Quadratic-Gaussian Systems	<i>D. Maity and P. Tsiotras</i>	382
Fixed-Time Projection Algorithm for Distributed Constrained Optimization on Time-Varying Digraphs	<i>G. Chen, Q. Yang, Y. Song, and F. L. Lewis</i>	390
Joint Sensor and Actuator Placement for Infinite-Horizon LQG Control	<i>L. Huang, J. Wu, Y. Mo, and L. Shi</i>	398
Unified Stability Analysis for Itô Stochastic Systems: From Almost Surely Asymptotic to Finite-Time Convergence	<i>S. Luo, F. Deng, and X. Yu</i>	406
Distributed Primal Decomposition for Large-Scale MILPs	<i>A. Camisa, I. Notarnicola, and G. Notarstefano</i>	413
An Accelerated Algorithm for Linear Quadratic Optimal Consensus of Heterogeneous Multiagent Systems	<i>Q. Wang, Z. Duan, J. Wang, Q. Wang, and G. Chen</i>	421
Exact Isoholonomic Motion of the Planar Purcell’s Swimmer	<i>S. Kadam, K. S. Phogat, R. N. Banavar, and D. Chatterjee</i>	429
Global Sampled-Data Regulation of a Class of Fully Actuated Invariant Systems on Simply Connected Nilpotent Matrix Lie Groups	<i>P. J. McCarthy and C. Nielsen</i>	436
Overapproximating Reachable Tubes of Linear Time-Varying Systems	<i>M. Serry and G. Reissig</i>	443
Robust Cooperative Output Regulation for a Network of Parabolic PDE Systems	<i>J. Deutscher</i>	451
Collisions-Free Distributed Optimal Coordination for Multiple Euler-Lagrangian Systems	<i>L. An and G.-H. Yang</i>	460
Controllability of a Linear System With Nonnegative Sparse Controls	<i>G. Joseph</i>	468
Design of Optimal Static Output Feedback Controllers for Linear Control Systems Subject to General Structural Constraints	<i>J.-L. Wu</i>	474
Multi-sensor Optimal Linear Estimation With Unobservable Measurement Losses	<i>H. Lin, Y. Li, J. Lam, and Z.-G. Wu</i>	481
Adaptive Control of Multivariable Networked Systems With Uncertain Time Delays	<i>M. Steinberger, M. Horn, and A. Ferrara</i>	489
Converse Barrier Functions via Lyapunov Functions	<i>J. Liu</i>	497
Robust Policy Iteration for Continuous-Time Linear Quadratic Regulation	<i>B. Pang, T. Bian, and Z.-P. Jiang</i>	504
Obstacle Avoidance via Hybrid Feedback	<i>S. Berkane, A. Bisoffi, and D. V. Dimarogonas</i>	512
Continuous-Time Linear Periodic Systems: A Note on the Controllability Interval Length	<i>V. Zaitsev</i>	520
Balanced Truncation of k -Positive Systems	<i>C. Grussler, T. Damm, and R. Sepulchre</i>	526
Limits to Energy Conversion	<i>A. van der Schaft and D. Jeltsema</i>	532
Addendum to “Converse Theorems for Integral Quadratic Constraints”	<i>S. Z. Khong and C.-Y. Kao</i>	539

IEEE TRANSACTIONS ON CONTROL SYSTEMS TECHNOLOGY



A PUBLICATION OF THE IEEE CONTROL SYSTEMS SOCIETY

JANUARY 2022

VOLUME 30

NUMBER 1

IETTE2

(ISSN 1063-6536)

REGULAR PAPERS

A Composite Single Particle Lithium-Ion Battery Model Through System Identification	<i>K. Gopalakrishnan and G. J. Offer</i>	1
Control of Very Lightweight 2-DOF Single-Link Flexible Robots Robust to Strain Gauge Sensor Disturbances: A Fractional-Order Approach	<i>D. Feliu-Talegon and V. Feliu-Battle</i>	14
Model Predictive Active Power Control for Optimal Structural Load Equalization in Waked Wind Farms	<i>M. Vali, V. Petrović, L. Y. Pao, and M. Kühn</i>	30
Accelerated Convergence Interleaving Iterative Learning Control and Inverse Dynamics Identification	<i>C.-W. Chen and T.-C. Tsao</i>	45
Distributed Integrated Control of a Mixed Traffic Network With Urban and Freeway Networks	<i>N. Wu, D. Li, and Y. Xi</i>	57
Sensor Selection for Dynamics-Driven User-Interface Design	<i>A. P. Vinod, A. J. Thorpe, P. A. Olaniyi, T. H. Summers, and M. M. K. Oishi</i>	71
LQR Control of an All-Wheel Drive Vehicle Considering Variable Input Constraint	<i>H. Jung, D. Jung, and S. B. Choi</i>	85
Distributed Demand Side Management With Stochastic Wind Power Forecasting	<i>P. Scarabaggio, S. Grammatico, R. Carli, and M. Dotoli</i>	97
Nonlinear MPC of a Heavy-Duty Diesel Engine With Learning Gaussian Process Regression	<i>D. Bergmann, K. Harder, J. Niemeyer, and K. Graichen</i>	113
Continuous Control Set Nonlinear Model Predictive Control of Reluctance Synchronous Machines	<i>A. Zanelli, J. Kullick, H. M. Eldeeb, G. Frison, C. M. Hackl, and M. Diehl</i>	130

(Contents Continued on Back Cover)



Incorporating Prior Knowledge in Local Parametric Modeling for Frequency Response Measurements: Applied to Thermal/Mechanical Systems	<i>E. Evers, B. de Jager, and T. Oomen</i>	142
Data-Driven Modeling and Design of Multivariable Dynamic Sliding Mode Control for the Underground Coal Gasification Project Thar	<i>S. B. Javed, V. I. Utkin, A. A. Uppal, R. Samar, and A. I. Bhatti</i>	153
Long-Horizon Vehicle Motion Planning and Control Through Serially Cascaded Model Complexity	<i>V. A. Laurence and J. C. Gerdes</i>	166
Distributed Model-Free Adaptive Predictive Control for Urban Traffic Networks	<i>D. Li and B. De Schutter</i>	180
Learning to Calibrate Quantum Control Pulses by Iterative Deconvolution	<i>X. Cao, B. Chu, Y.-X. Liu, Z. Peng, and R.-B. Wu</i>	193
Indirect/Direct Learning Coverage Control for Wireless Sensor and Mobile Robot Networks	<i>Y.-C. Liu, T.-C. Lin, and M.-T. Lin</i>	202
Sensorless Optimal Interaction Control Exploiting Environment Stiffness Estimation	<i>L. Roveda, A. A. Shahid, N. Iannacci, and D. Piga</i>	218
Iterative Learning Control for Path-Following Tasks With Performance Optimization	<i>Y. Chen, B. Chu, and C. T. Freeman</i>	234
f ² IMU-R: Pedestrian Navigation by Low-Cost Foot-Mounted Dual IMUs and Interfoot Ranging	<i>M. Zhu, Y. Wu, and S. Luo</i>	247
Formation Control With Time-Varying Formations, Bounded Controls, and Local Collision Avoidance	<i>Z. S. Lippay and J. B. Hoagg</i>	261
Prediction-Based Control for Mitigation of Axial–Torsional Vibrations in a Distributed Drill-String System	<i>S. Tashakori, G. Vossoughi, H. Zohoor, and N. van de Wouw</i>	277
Reset PID Design for Motion Systems With Stribeck Friction	<i>R. Beerens, A. Bisoffi, L. Zaccarian, H. Nijmeijer, M. Heemels, and N. van de Wouw</i>	294
Application of Structured Robust Synthesis for Flexible Aircraft Flutter Suppression	<i>B. Patartics, G. Lipták, T. Luspay, P. Seiler, B. Takarics, and B. Vanek</i>	311
Shared Control With Efficient Subgoal Identification and Adjustment for Human–Robot Collaborative Tasks	<i>Z. Jin and P. R. Pagilla</i>	326

BRIEF PAPERS

Event-Triggered Formation Control for a Class of Uncertain Euler–Lagrange Systems: Theory and Experiment	<i>X. Jin, Y. Tang, Y. Shi, W. Zhang, and W. Du</i>	336
Analysis of Networked Structural Control With Packet Loss	<i>T. H. T. Truong, P. Seiler, and L. E. Linderman</i>	344
Model Predictive Control of Priced Timed Automata Encoded With First-Order Logic	<i>E. C. Balta, I. Kovalenko, I. A. Spiegel, D. M. Tilbury, and K. Barton</i>	352
Optimal Switching Time Control for Suppressing Residual Vibration in a High-Speed Macro-Micro Manipulator System	<i>T. Chen, J. Lou, Z. Ren, and Y. Wei</i>	360
Integrated Clutch Torque Control and Touchpoint Estimation Using Deadbeat Adaptive Backstepping	<i>W. Wei, H. Dourra, and G. Zhu</i>	368
Stochastic Optimal Control of HVAC System for Energy-Efficient Buildings	<i>Y. Yang, G. Hu, and C. J. Spanos</i>	376
Toward Model-Based Control of the Vertical Gradient Freeze Crystal Growth Process	<i>S. Ecklebe, F. Woittennek, C. Frank-Rotsch, N. Dropka, and J. Winkler</i>	384
Performance Analysis of Series Elastic Actuator Based on Maximum Torque Transmissibility	<i>C. Lee and S. Oh</i>	392
Distributed Surrounding Control of Multiple Unmanned Surface Vessels With Varying Interconnection Topologies	<i>B.-B. Hu, H.-T. Zhang, B. Liu, H. Meng, and G. Chen</i>	400
Port-Hamiltonian Flight Control of a Fixed-Wing Aircraft	<i>J.-M. Fahmi and C. A. Woolsey</i>	408
Distributed Time-Varying Optimization With State-Dependent Gains: Algorithms and Experiments	<i>S. Sun, Y. Zhang, P. Lin, W. Ren, and J. A. Farrell</i>	416
Distributed Voltage Regulation for Low-Voltage and High-PV-Penetration Networks With Battery Energy Storage Systems Subject to Communication Delay	<i>L. Xing, Y. Mishra, Y.-C. Tian, G. Ledwich, C. Wen, W. He, W. Du, and F. Qian</i>	426
Stability Analysis of Sampled-Data Load Frequency Control Systems With Multiple Delays	<i>H. Luo and Z. Hu</i>	434
Real-Time Road Bank Estimation With Disturbance Observers for Vehicle Control Systems	<i>E. Hashemi, A. Khajepour, N. Moshchuk, and S.-K. Chen</i>	443

IEEE TRANSACTIONS ON CONTROL OF NETWORK SYSTEMS

A PUBLICATION OF THE IEEE CONTROL SYSTEMS SOCIETY



COSPONSORED BY
IEEE CIRCUITS AND SYSTEMS SOCIETY
IEEE COMMUNICATIONS SOCIETY
IEEE COMPUTER SOCIETY
IEEE ROBOTICS AND AUTOMATION SOCIETY



DECEMBER 2021

VOLUME 08

NUMBER 4

ITCNAY

(ISSN 2325-5870)

REGULAR PAPERS

Discrete-Time Matrix-Weighted Consensus	<i>Q. Van Tran, M. H. Trinh, and H.-S. Ahn</i>	1568
Stabilizing a Queue Subject to Activity-Dependent Server Performance	<i>M. Lin, R. J. La, and N. C. Martins</i>	1579
Optimal Sampling Pattern for the Free Final Time Linear Quadratic Regulator	<i>P. Balaguer and C. Ariño</i>	1592
Diffusion and Consensus in a Weakly Coupled Network of Networks	<i>Y. Yi, A. Das, B. Bamieh, Z. Zhang, and S. Patterson</i>	1601
Remote State Estimation With a Strategic Sensor Using a Stackelberg Game Framework	<i>Y. Ni, X. Ren, S. Dey, and L. Shi</i>	1613
A Unified Dissertation on Bearing Rigidity Theory	<i>G. Michieletto, A. Cenedese, and D. Zelazo</i>	1624
Rebalancing Self-Interested Drivers in Ride-Sharing Networks to Improve Customer Wait-Time	<i>A. S. Yengejeh and S. L. Smith</i>	1637
Localization of Invariable Sparse Errors in Dynamic Systems	<i>D. Kahl, A. Weber, and M. Kschischo</i>	1649
A Revisit to the Controllability and Observability of Networked Dynamic Systems	<i>Y. Zhou and T. Zhou</i>	1659
Moving-Target Enclosing Control for Mobile Agents With Collision Avoidance	<i>L. Dou, X. Yu, L. Liu, X. Wang, and G. Feng</i>	1669
Rethinking Power Control in Wireless Networks: The Perspective of Satisfaction Equilibrium	<i>P. Promponas, E. E. Tsiropoulou, and S. Papavassiliou</i>	1680
Security Analysis of Linearization for Nonlinear Networked Control Systems Under DoS	<i>R. Kato, A. Cetinkaya, and H. Ishii</i>	1692
Robustness of Networked Systems to Unintended Interactions With Application to Engineered Genetic Circuits	<i>Y. Qian and D. Del Vecchio</i>	1705
Incentivizing Efficient Equilibria in Traffic Networks With Mixed Autonomy	<i>E. Bıyık, D. A. Lazar, R. Pedarsani, and D. Sadigh</i>	1717
Clustering Switching Regions for Feedback Controllers: A Convex Approach	<i>P. Chanfreut, J. M. Maestre, F. J. Muros, and E. F. Camacho</i>	1730

(Contents Continued on Page 1567)



Robust Cooperative Control of Networked Train Platoons: A Negative-Imaginary Systems' Perspective	1743
..... <i>C. Li, J. Wang, J. Shan, A. Lanzon, and I. R. Petersen</i>	
Performance Bounds for Optimal and Robust Feedback Control in Networks	1754
..... <i>K. Ganapathy, J. Ruths, and T. Summers</i>	
Cooperative Startup Control for Heterogeneous Vehicle Platoons: A Finite-Time Output Tracking-Based Approach	1767
..... <i>C. Du, Y. Bian, H. Liu, W. Ren, P. Lu, and X. Liu</i>	
Modeling and Dynamics of Networked Evolutionary Game With Switched Time Delay	1778
..... <i>Y. Zheng, C. Li, and J.-e Feng</i>	
On Periodic Scheduling and Control for Networked Systems Under Random Data Loss	1788
..... <i>A. Kundu and D. E. Quevedo</i>	
Distributed Policy Synthesis of Multiagent Systems With Graph Temporal Logic Specifications	1799
..... <i>M. Cubuktepe, Z. Xu, and U. Topcu</i>	
Global Exponential Stability Analysis of Coupled Cyclic Genetic Regulatory Networks With Constant Delays	1811
..... <i>Z. Liu, X. Yang, T. Yu, X. Zhang, and X. Wang</i>	
A Unified Analytical Framework for Optimal Control Problems on Networks With Input Homogeneity	1822
..... <i>M. Li and H. Dankowicz</i>	
Parallel Learning of Koopman Eigenfunctions and Invariant Subspaces for Accurate Long-Term Prediction	1833
..... <i>M. Haseli and J. Cortés</i>	
Non-normality Improves Information Transmission Performance of Network Systems	1846
..... <i>G. Baggio and S. Zampieri</i>	
Throughput Optimal Routing in Blockchain-Based Payment Systems	1859
..... <i>S. M. Varma and S. T. Maguluri</i>	
Robust Coalitional Model Predictive Control With Predicted Topology Transitions	1869
..... <i>E. Maserò, J. M. Maestre, A. Ferramosca, M. Francisco, and E. F. Camacho</i>	
Adaptive Event-Triggered Strategy for Economic Dispatch in Uncertain Communication Networks	1881
..... <i>Y. Wan, C. Long, R. Deng, G. Wen, and X. Yu</i>	
Stochastic Distributed Predictive Tracking Control Under Inexact Minimization	1892
..... <i>C. Mark and S. Liu</i>	
Sample Complexity of Block-Sparse System Identification Problem	1905
..... <i>S. Fattahi and S. Sojoudi</i>	
Attack Detection and Distributed Filtering for State-Saturated Systems Under Deception Attack	1918
..... <i>L. Li, H. Yang, Y. Xia, and C. Zhu</i>	
A Convexification Approach for Small-Signal Stability Constrained Optimal Power Flow	1930
..... <i>P. Pareek and H. D. Nguyen</i>	
Smoothed-Particle-Hydrodynamics for the Control of Robotic Swarms, and Parametric Associations	1942
..... <i>Y. B. Mitikiri, M. Silic, and K. Mohseni</i>	
Distributed Optimization of Second-Order Nonlinear Multiagent Systems With Event-Triggered Communication	1954
..... <i>S. Li, X. Nian, and Z. Deng</i>	
PdI Regulation for Consensus: Application to Unknown Pure-Feedback Agents With State and Communication Delays	1964
..... <i>A. K. Gkesoulis, H. E. Psillakis, and Q. Wang</i>	
Control Policies for Recovery of Interdependent Systems After Disruptions	1975
..... <i>H. Gehlot, S. Sundaram, and S. V. Ukkusuri</i>	

CORRECTION

Corrections to "Safe Affine Transformation-Based Guidance of a Large-Scale Multiquadcopter System"	1987
..... <i>H. Rastgoftar and I. V. Kolmanovsky</i>	

UPCOMING CONFERENCES



American Control Conference **ACC 2022**

June 8–10, Atlanta, GA, USA

LCSS Option Submission

September 14, 2021 (Passed)

Manuscript Submission

September 28, 2021 (Passed)

Acceptance/Rejection Notice

January 24, 2022

Final Manuscript Submission

March 15, 2022

<https://acc2022.a2c2.org/>



Conference on Control Technology and Applications **CCTA 2022**

August 23–25, Trieste, Italy

Paper Submission Due:

February 1, 2022

Decision Notification:

April 22, 2022

Registration Opens:

Middle of May, 2022

Final Submissions:

Middle of June, 2022

<https://ccta2022.ieeecss.org/>



Conference on Decision and Control CDC 2022

December 6–9, Cancun, Mexico

Initial Paper to L-CSS with CDC option
March 7, 2022

Invited Session Proposals
March 14, 2022

Initial Paper Submission
March 21, 2022

Workshop Proposals
May 2, 2022

Decision Notification
Mid-July, 2022

Final Submission
September 21, 2022

<https://cdc2022.ieeecss.org/>



American Control Conference **ACC 2023**

May 31 – June 2, San Diego, CA, USA

LCSS Option Submission
September 9, 2022

Manuscript Submission
September 23, 2022

Acceptance/Rejection Notice
January 22, 2023

Final Manuscript Submission
March 13, 2023

<https://acc2023.a2c2.org/>